

IMU (Inertial Measurement Unit) RS422 INTERFACE

■ GENERAL DESCRIPTION

The M-G552PR7 is a small form factor inertial measurement unit (IMU) with 6 degrees of freedom: tri-axial angular rates and linear accelerations, and provides high-stability and high-precision measurement capabilities with the use of high-precision compensation technology.

A variety of calibration parameters are stored in memory of the IMU, and are automatically reflected in the measurement data being sent to the application after the power of the IMU is turned on.

With RS422 interface support for host communication, the M-G552PR7 reduces technical barriers for users to introduce inertial measurement and minimizes design resources to implement inertial movement analysis and control applications. This unit is packaged in a water-proof and dust-proof metallic case. It is suitable for use in industrial and heavy duty applications.

The features of the IMU such as high stability, high precision, and small size make it easy to create and differentiate applications in various fields of industrial systems.

■ FEATURES

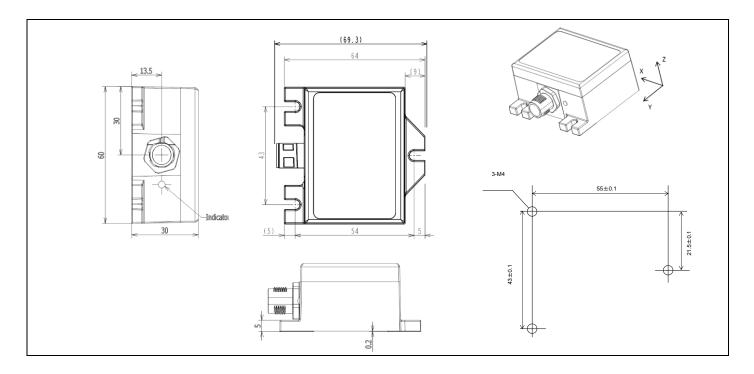
Item	Specification	
Sensor		
Integrated sensor	SEIKO EPSON inertial measurement sensor	
	Low-Noise, High-stability	
	Gyro Bias Instability : 0.8 °/h	
	Angular Random Walk : 0.06 °/√h	
	Initial Bias Error : 360 °/h (1σ)/ 3 mG(1σ)	
	6 Degree Of Freedom	
	Triple Gyroscope : ±450 °/s	
	Tri-Axis Accelerometer : ±10 G	
	16bit data resolution	
	Calibrated Stability (Bias, Scale Factor, Axial Alignment)	
Interface		
Protocol (DL layer)	RS-422 (TX/RX Pair, Full-Duplex transmission)	
Bit rate	Maximum 460.8kbps (default) 230.4kbps (programable)	
Cable Length	250m (max)	
Terminator	Included (120Ωtyp)	
Environment		
Voltage supply	9 V to 32 V	
Power consumption	42 mA	
Operating temperature range	-30 °C to +80 °C	
External dimension		
Outer packaging	Overall metallic shield case	
Size	65 x 60 x 30 mm ³ (Not including projection.)	
Weight	115 g	
Interface connector	M12, 8pin-male, waterproof	
Waterproof, Dustproof:	IP67 equivalent	
Random vibration	1 hour at 20Grms	
	MIL-STD-810, METHOD 514.x ANNEX E, Category24	
Sine sweep vibration	4 hours / axis at 10G	
	MIL-STD-202G, METHOD 204	
Mechanical shock	1,000G, Half-sine 0.5ms, once per ±each axis(6times)	

Ite	em	Specification
Regulation		
	EU	CE marking (EN61326/RoHS Directive) Class A
	USA	FCC part15B Class A

■ APPLICATIONS

- Motion and Vibration Measurement
- Platform Stabilization
- Attitude Detection for Unmanned Systems Vibration Control and Stabilization

■ OUTLINE DIMENSION



Outline Dimensions (millimeters)

M-G552PR7



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